

Team Match Form

euRathlon 2015
Piombino, Italy, September 2015

Team Details

Team's Name:

Institution/Company:

Website:

Home location of team:

Picture of the team:



Name of team leader (contact):

Contact E-mail:

Team Description

When the team was established (year):

2015

Domains (expertise, years):

teleoperation 3, autonomous motion 2

Team Description:

The OUBOT team is formed by three teams from the Antal Bejczy Center for Intelligent Robotics (ABC), John von Neumann Faculty of Informatics (NIK) and Biotech Knowledge Center (BTTK) of Obuda University. Basically ABC has strong expertise in human like robots, NIK is strong in UAVs and BTTK is good in programming and DAQ.

Major achievements (*i.e. SLAM mapping of indoor building with a flying quadrotor*):

virtual modeling, teleoperation and autonomous motion of a KUKA youBot

Experience in other competitions (name, year, classification):

Have you attended previous euRathlon competitions and/or workshops? (name/year):

no

Looking for teams

Domains:

Land

Sea

Air

Please, indicate any requirements or preferences:

(i.e. an UAV with hovering capabilities and an autonomy of at least 15 minutes)

I attach to this form the following number of vehicle's specification sheets:

UGV

USV

AUV

UAV

Send form to: eurathlon@uwe.ac.uk

Subject: "Your_team_name - euRathlon 2015 Team Match"

NOTE: All the information in this form will be stored on an internal data base and only will be given to those teams which the organisation believes are good candidates for a team match.